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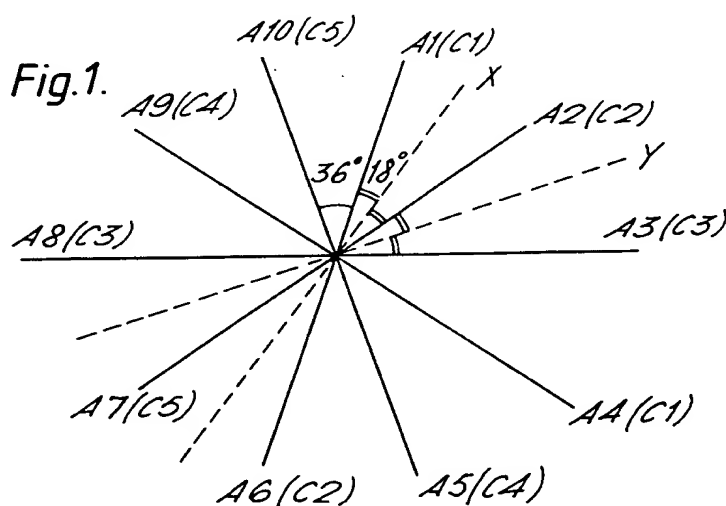
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(54) Direction finding using a plurality of aerials

(57) Direction finding apparatus comprising at least ten antenna channels for connection to respective antennae in use, at least five receiver channels each coupled to at least two different antenna channels constituting a group, and means for receiving and comparing the outputs of the receiver channels to determine the angular location of the signal source; the arrangement being such that in use the antennae of each group of antenna channels have a sufficient angular separation such that only one is capable of detecting the signal source at one time, and the nearest neighbouring antennae of each group are coupled to respective different receiver channels different from the receiver channel of that group.



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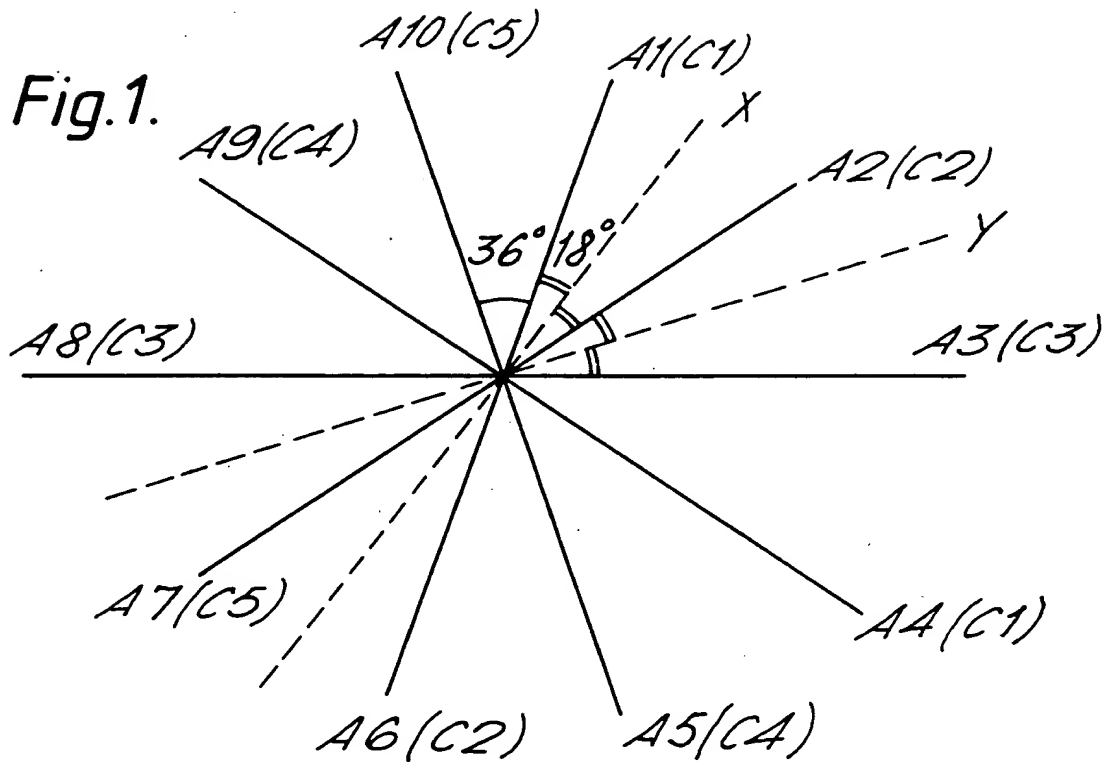
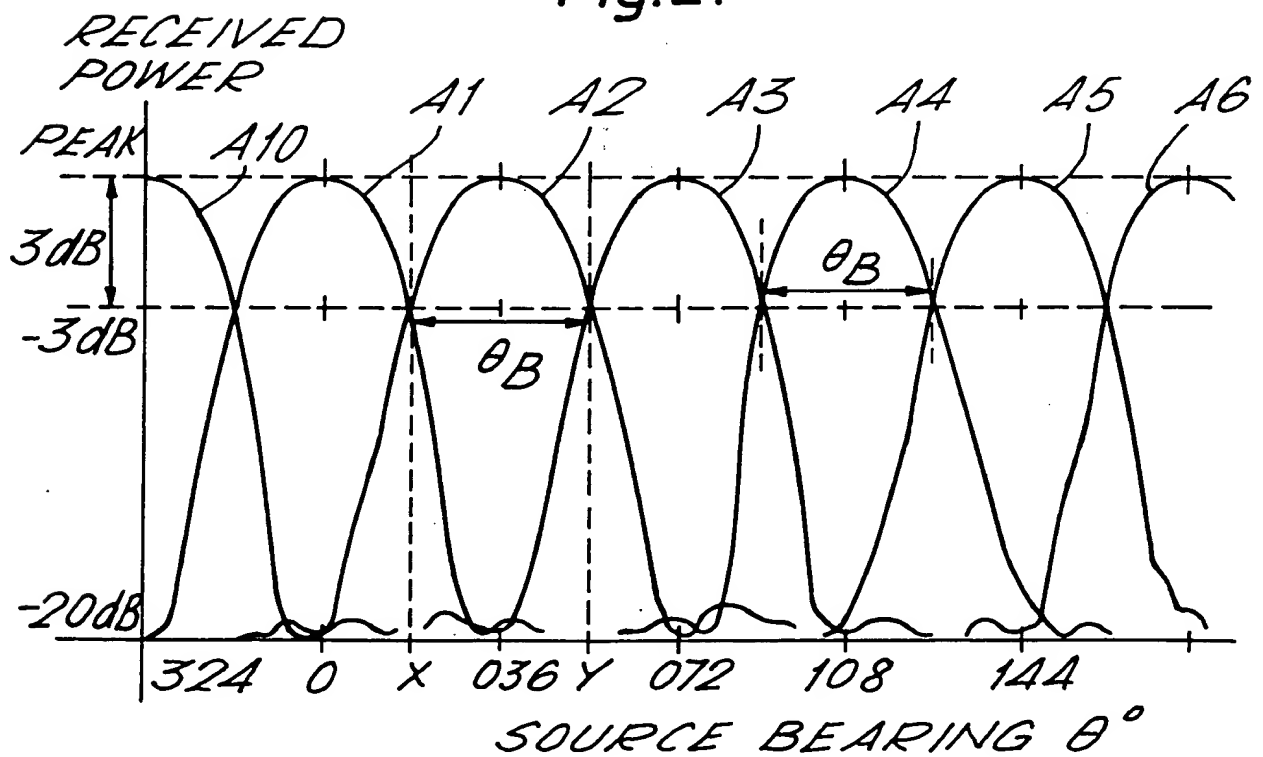
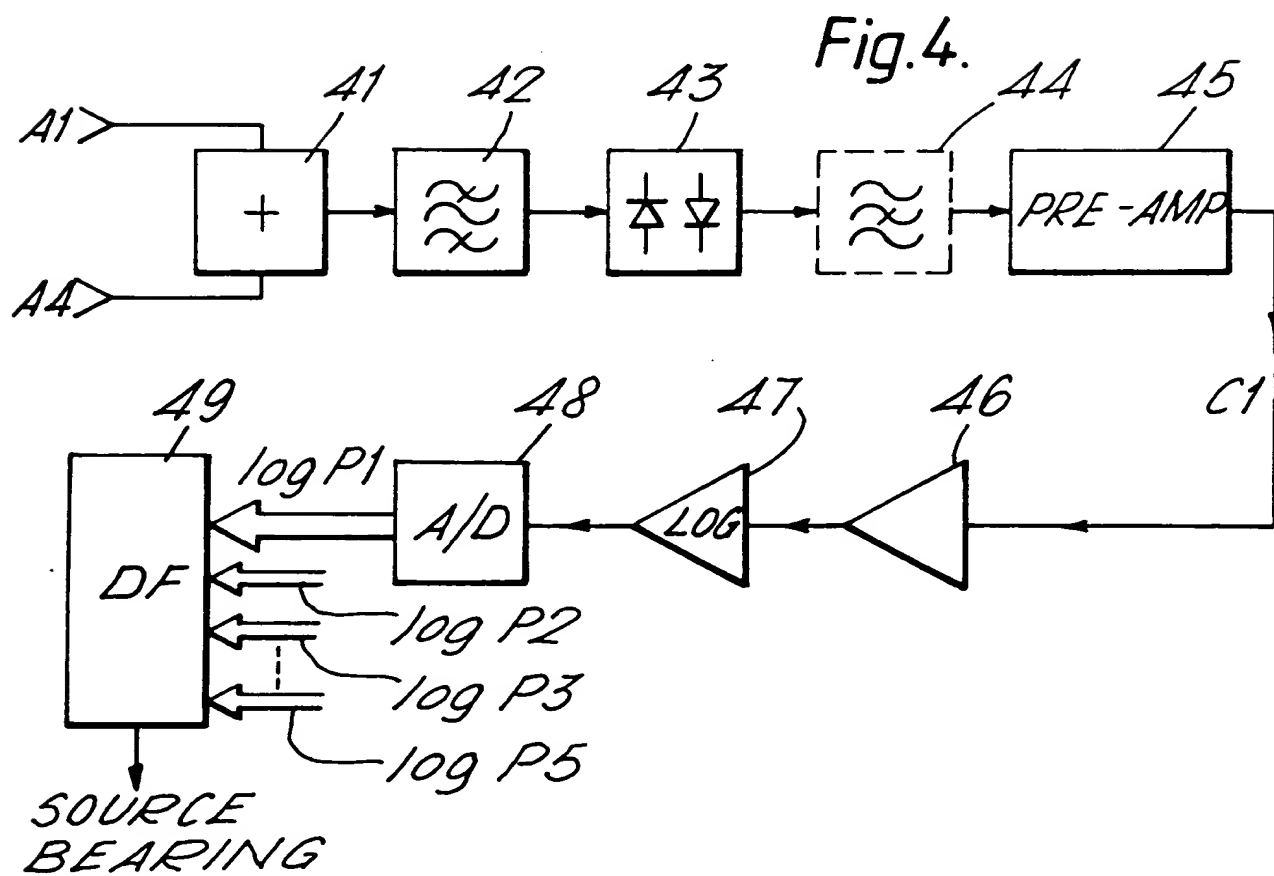
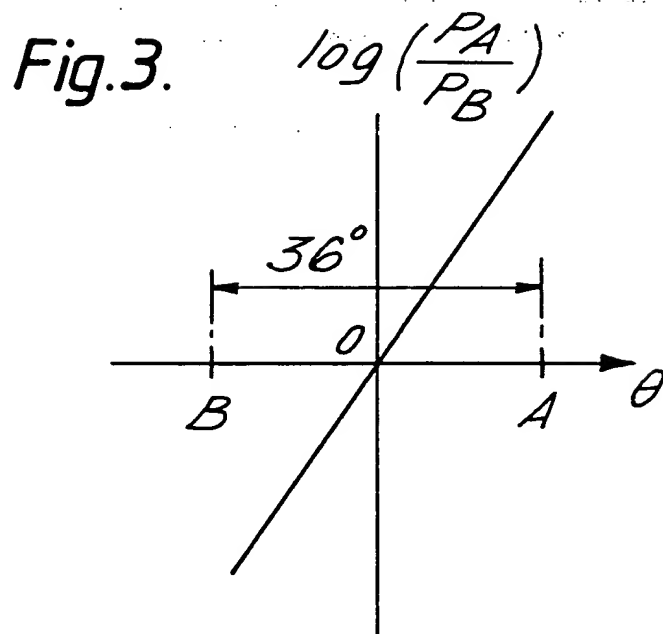


Fig.2.





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DFS/3481Direction Finding

This invention relates to direction finding (DF) apparatus for use with directional antennae pointing at a multiplicity of different angles. Such DF apparatus typically detects a localised source of radio-frequency radiation using antennae and receivers suited to the particular waveband of interest, and the antenna boresights are typically coplanar, but the invention is applicable to other DF systems.

Known DF apparatus comprises several antennae, with coplanar boresight axes coinciding at a point, the antennae spaced equi-angularly to obtain 360° cover in one plane. The angular separation is typically equal to the 3dB beamwidth of each antenna, i.e. the angle bounding a sector within which the power received by the antenna is within 3dB of its maximum.

Such conventional apparatus locates a radiation source by first determining the angular sector in which the received signal is strongest, and then comparing the received powers from the two antennae whose boresights bound that angular sector, in order to determine the angular position of the source within that sector. The expected variation of this power ratio with source angle is a known quantity, and it is usually possible to locate a source to an accuracy of one tenth of an angular beamwidth or sector width.

It is not normally possible to increase the angular

separation of the antennae much beyond the beamwidth because this increases the dynamic range requirements of the receiver and requires exceptional control of the antenna pattern. It follows that in order to achieve a better DF accuracy over a given field of view more receiver channels would have to be used and the cost of the overall receiver would increase rapidly.

The invention provides direction finding apparatus comprising at least ten antenna channels for connection to respective antennae in use, at least five receiver channels each coupled to at least two different antenna channels constituting a group, and means for receiving and comparing the outputs of the receiver channels to determine the angular location of the signal source; the arrangement being such that in use the antennae of each group of antenna channels have a sufficient angular separation such that at most one is capable of receiving significant signal power from a point source at one time, and the nearest neighbouring antennae of each group are coupled to respective different receiver channels different from the receiver channel of that group.

One way in which the invention may be performed will now be described, by way of example only, with reference to the accompanying schematic drawings, in which:

Figure 1 is a representation of the angular disposition in a horizontal plane of a ten-antenna DF system embodying the invention,

Figure 2 is a graph of the power received from a point source in several of the antennae of Figure 1, as a function of the angular position θ of the source,

Figure 3 is a graph of the variation with source angle θ of the logarithm of the power ratio between two adjacent antennae A and B both receiving radiation from the same source, and

Figure 4 is a block diagram of one pair of antenna channels and one receiver channel of the system of Figures 1 and 2.

The simplest system embodying the invention is illustrated in Figure 1, and comprises ten similar antennae spaced equi-angularly in a horizontal plane, with their boresight axes A1 to A10 intersecting at a point. The antennae are directional and point radially

outwardly, in order to scan the full 360° range in that plane. The antennae are coupled to ten respective antenna channels A1 to A10, whose outputs are combined into pairs to form five receiver channels C1 to C5, coupled to five respective receivers. The coupling between the antenna channels and the receiver channels is in accordance with two general rules, described below, which together ensure that the angular discriminating ability of the system is optimised. The outputs from the receivers are then treated in much the same way as are the antenna channel outputs in the conventional DF apparatus described above. Thus the powers of all channels are compared to identify the angular sector in which the signal received is strongest, and the powers of the two strongest channels are compared to determine the angular position of the source within that sector.

The general rules for the grouping of the antenna channels for coupling to the respective receiver channels are as follows:-

First, the antennae of each pair or group must have an angular separation sufficient to prevent interference, such that a signal received in one antenna must not be received simultaneously in the other or others. The threshold of reception may be defined conveniently as, say 20dB or 30dB below the peak reception power. Where the antennae are separated by an angle equal to the 3dB beamwidth, it is preferable to arrange that the antennae of each pair or group are separated mutually by at least three beamwidths, i.e. there are always at least two intermediate antennae of other pairs or groups.

Secondly, the nearest neighbouring antennae of all the antennae of each pair or group must be coupled to a distinct receiver channel, different from the receiver channel of the pair or group in question.

Table 1 below indicates the coupling between the antennae A1 to A10 of Figures 1 and 2 and the five receiver channels C1 to C5, in accordance with the labelling C1 to C5 on Figure 1.

TABLE 1:

Antenna (A)	1	2	3	4	5	6	7	8	9	10
Channel (C)										
1	X			X						
2		X				X				
3			X					X		
4					X				X	
5							X			X

With reference to Figure 2, it is apparent that the second rule is satisfied in the case of channel C1 because the nearest neighbouring antennae to antennae A1 and A4, i.e. A10 and A2, A3 and A5, are all coupled to different channels, i.e. to C5, C2, C3 and C4 respectively.

With reference to Figures 1 and 2, the 3dB beamwidth θ_B coincides with the angular separation of the antennae, and is equal to 36° . A source detected at the angle X, bisecting the axes A1 and A2, is on the 3dB threshold of both antennae A1 and A2, and will be received with equal power in channels C1 and C2, to which a negligible contribution is made by antennae A4 and A6 respectively, the other members of the pairs. The logarithm of the power ratio of the received signals on channels C1 and C2 will be zero, corresponding correctly to the centre of the angular range of Figure 3, assuming P_A and P_B to be C1 and C2, and A1 and A2 to be A and B. If the source had been between X and A1, still within the sector A1 - A2, then by reference to Figure 3 the result would be a positive logarithm indicating the appropriate angular location within that sector. The

crude location of the source is determined as being within the sector A1 - A2, and not any of the larger sectors A1 - A6, A2 - A4 and A4 - A6, all involving combinations of the antennae of channels C1 and C2, because channels C1 and C2 have higher received powers than any of channels C3, C4, C5. Thus, as described in greater detail below, the means for comparing and processing the outputs from the receiver channels C1 to C5 is programmed with the information corresponding to Table 1 necessary for it to identify the unique sector in which the source is located.

Antennae A1 and A4 are shown in Figure 4 coupled to receiver channel C1, which in turn provides a digital output $\log P_1$ representative of the logarithm of the received power to the DF comparing and processing means 49, which receives corresponding outputs $\log P_2$ to $\log P_5$ from the other four receiver channels, and determines the source bearing. The outputs from the antenna channels A1 and A4 are combined at 41 and the combined signal is typically fed through a band pass filter 42, a limiter 43, a YIG filter 44, pre-amplifier or down-converter 45 (with an architecture to suit crystal video receiver or superheterodyne applications), a further amplifier 46 and high dynamic range log amplifier 47, and an analogue-to-digital converter 48.

The DF comparing and processing means 49 determines the highest ($\log P_A$) and second highest ($\log P_B$) of the receiver channel outputs, and then computes the source bearing according to the formula:

$$(\text{Sector angle}) + \text{SIGN. } K. (\log P_A - \log P_B)$$

where K is the tracking slope of approximately 1.5 degrees per decibel, i.e. the slope of the graph of Figure 3, and the quantities (Sector Angle) and SIGN are read out from the following table, which assumes that the relationship of Figure 3 is general to all adjacent antennae:-

TABLE 2

Receiver Channel Providing P_A	Receiver Channel Providing P_B	Sector Angle	SIGN.
C1	C3	90	+1
C1	C5	342	+1
C2	C1	18	+1
C2	C4	162	+1
C3	C2	54	+1
C3	C5	234	+1
C4	C1	126	+1
C4	C3	270	+1
C5	C4	306	+1
C5	C2	198	+1
C1	C2	18	-1
C1	C4	126	-1
C2	C3	54	-1
C2	C5	198	-1
C3	C1	90	-1
C3	C4	270	-1
C4	C2	162	-1
C4	C5	306	-1
C5	C1	342	-1
C5	C3	234	-1

Thus, in the case where channels C1 and C2 are the highest and second highest respectively in power, the source bearing is computed as:

$$(18^\circ) + (-1) \cdot (1.5) \cdot (\log P_A - \log P_B),$$

which is between X (at 018°) and A1 (at 0°).

Bearings are taken relative to the boresight A1.

The DF accuracy of this ten antenna, five receiver channel system is as good as a conventional system with ten receiver channels. The apparatus could comprise a larger number of antennae, with a number of

receiver channels equal to a rational fraction of that number: using the invention, the DF accuracy of an n antenna system can be achieved with $n/2$, or $n/3$, etc. receiver channels, provided only that the two general rules are satisfied. Table 3 below is one example of a twelve antenna system where the antenna channels are paired, and Table 4 below is one example of a twenty-one antenna system in which the antenna channels are in groups of three, coupled to seven receiver channels. Three-way combining is only possible with twenty-one, or a larger multiple of three, antenna channels.

TABLE 3

Antenna (A)	1	2	3	4	5	6	7	8	9	10	11	12
Channel (C)												
1	X					X						
2		X						X				
3			X							X		
4				X								X
5					X				X			
6							X				X	

TABLE 4

Antenna (A)																					
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21
Channel (C)																					
1		X			X			X													
2												X					X				X
3				X		X							X								
4							X			X						X					
5								X						X				X			
6				X											X						X
7		X									X								X		

Although the invention has been illustrated by apparatus with coplanar antennae in a horizontal plane, extending the full 360° of azimuth, clearly the invention is applicable to other systems; for example, there may be banks of such antennae whose outputs are combined to provide triangulation to locate absolutely the source, and the antennae may be capable of scanning. The apparatus may also be capable of transmitting signals, for example monopulse radar or sonar signals, to locate targets which reflect but are not radiation sources.

CLAIMS

1. Direction finding apparatus comprising at least ten antenna channels for connection to respective antennae in use, at least five receiver channels each coupled to at least two different antenna channels constituting a group, and means for receiving and comparing the outputs of the receiver channels to determine the angular location of the signal source; the arrangement being such that in use the antennae of each group of antenna channels have a sufficient angular separation such that at most one is capable of receiving significant power from a point source at one time, and the nearest neighbouring antennae of each group are coupled to respective different receiver channels different from the receiver channel of that group.
2. Apparatus according to Claim 1 comprising at least ten antennae coupled to respective antenna channels in the arrangement as claimed in Claim 1.
3. Apparatus according to Claim 2, in which the minimum angular separation of the antennae is three 3dB beamwidths of the antennae.
4. Apparatus according to Claim 2 or 3, in which the antenna boresight axes are coplanar.
5. Apparatus according to Claim 2, 3 or 4, in which the antenna boresight axes coincide at a point.
6. Apparatus according to any of Claims 2 to 5, in which the antenna boresight axes are disposed equi-angularly about a central point.
7. Direction finding apparatus according to any preceding claim and arranged in accordance with Table 1.
8. Direction finding apparatus according to any preceding claim and arranged in accordance with Table 3.
9. Direction finding apparatus according to any preceding claim and arranged in accordance with Table 4.
10. Direction finding apparatus substantially as described herein with reference to the accompanying drawings.

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